

University College London
Department of Physics and Astronomy
2B21 Mathematical Methods in Physics & Astronomy
Suggested Solutions for Problem Sheet M2 (2003–2004)

1. In matrix notation

$$\underline{r}_2 = \underline{A} \underline{r}_1 \quad \text{and} \quad \underline{r}_3 = \underline{B} \underline{r}_2 ,$$

where

$$\underline{A} = \begin{pmatrix} \frac{1}{\sqrt{2}} & 0 & -\frac{1}{\sqrt{2}} \\ \frac{1}{2} & -\frac{1}{\sqrt{2}} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{\sqrt{2}} & \frac{1}{2} \end{pmatrix} \quad \text{and} \quad \underline{B} = \begin{pmatrix} 0 & \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & -\frac{1}{2} & -\frac{1}{2} \\ -\frac{1}{\sqrt{2}} & \frac{1}{2} & \frac{1}{2} \end{pmatrix} . \quad [2]$$

Hence

$$\underline{r}_3 = \underline{B} \underline{A} \underline{r}_1 = \underline{C} \underline{r}_1 ,$$

where

$$\underline{C} = \begin{pmatrix} 0 & \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & -\frac{1}{2} & -\frac{1}{2} \\ -\frac{1}{\sqrt{2}} & \frac{1}{2} & \frac{1}{2} \end{pmatrix} \begin{pmatrix} 0 & \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & -\frac{1}{2} & -\frac{1}{2} \\ -\frac{1}{\sqrt{2}} & \frac{1}{2} & \frac{1}{2} \end{pmatrix} = \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} . \quad [3]$$

The new components are therefore

$$x_3 = y_1 , \quad y_2 = -x_1 , \quad z_3 = z_1 . \quad [1]$$

The resultant rotation is 90° about the z -axis. [1]

2. The simultaneous equations are

$$\begin{aligned} 3x_1 - 2x_2 - x_3 &= 4 , \\ 2x_1 + x_2 + 2x_3 &= 10 , \\ x_1 + 3x_2 - 4x_3 &= 5 . \end{aligned}$$

The determinant of the matrix is

$$\Delta = |\underline{A}| = \begin{vmatrix} 3 & -2 & -1 \\ 2 & 1 & 2 \\ 1 & 3 & -4 \end{vmatrix} = 3(-4 - 6) + 2(-8 - 2) - 1(6 - 1) = -55 . \quad [2]$$

By Cramer's rule,

$$\Delta \times x_1 = \begin{vmatrix} 4 & -2 & -1 \\ 10 & 1 & 2 \\ 5 & 3 & -4 \end{vmatrix} = 4(-4 - 6) + 2(-4 - -10) - (30 - 5) = -40 - 100 - 25 = -165.$$

Hence $x_1 = 3$. [2]

$$\Delta \times x_2 = \begin{vmatrix} 3 & 4 & -1 \\ 2 & 10 & 2 \\ 1 & 5 & -4 \end{vmatrix} = 3(-40-10) - 4(-8-2) - (10-10) = -150 + 40 = -110.$$

Hence $x_2 = 2$.

[2]

$$\Delta \times x_3 = \begin{vmatrix} 3 & -2 & 4 \\ 2 & 1 & 10 \\ 1 & 3 & 5 \end{vmatrix} = 3(5-30) + 2(10-10) + 4(6-1) = -55.$$

Hence $x_1 = 1$.

[2]

3. The determinant of the matrix is

$$|\underline{A}| = \begin{vmatrix} 1 & 3 & 1 \\ 1 & 1 & 2 \\ 3 & 3 & 2 \end{vmatrix} = \begin{vmatrix} 1 & 3 & 1 \\ 0 & -2 & 1 \\ 0 & -6 & -1 \end{vmatrix} = 8.$$

The cofactor matrix is

$$\underline{C} = \begin{pmatrix} -4 & 4 & 0 \\ -3 & -1 & 6 \\ 5 & -1 & -2 \end{pmatrix}. \quad [3]$$

The adjoint matrix is merely the transpose of \underline{C} ;

$$\underline{A}^{\text{adj}} = \underline{C}^T = \begin{pmatrix} -4 & -3 & 5 \\ 4 & -1 & -1 \\ 0 & 6 & -2 \end{pmatrix}. \quad [1]$$

Hence the inverse matrix

$$\underline{A}^{-1} = \frac{1}{|\underline{A}|} \underline{A}^{\text{adj}} = \frac{1}{8} \begin{pmatrix} -4 & -3 & 5 \\ 4 & -1 & -1 \\ 0 & 6 & -2 \end{pmatrix}. \quad [1]$$

Thus

$$\begin{aligned} \underline{B} &= \underline{A}^{-1} \underline{D} = \frac{1}{8} \begin{pmatrix} -4 & -3 & 5 \\ 4 & -1 & -1 \\ 0 & 6 & -2 \end{pmatrix} \begin{pmatrix} 10 & -6 & 6 \\ 9 & -6 & 5 \\ 15 & -10 & 11 \end{pmatrix} \\ &= \begin{pmatrix} (-40 - 27 + 75) & (24 + 18 - 50) & (-24 - 15 + 55) \\ (40 - 9 - 15) & (-24 + 6 + 10) & (24 - 5 - 11) \\ 0 + 54 - 30 & (0 - 36 + 20) & (0 + 30 - 22) \end{pmatrix} = \begin{pmatrix} 1 & -1 & 2 \\ 2 & -1 & 1 \\ 3 & -2 & 1 \end{pmatrix}. \end{aligned}$$

[3]