

# Engineering Mathematics III Summary Sheet 9

## Approximate Methods for ODEs

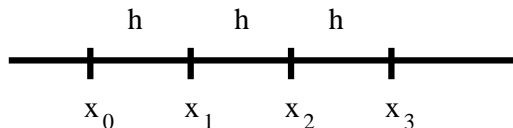
### 1 Numerical Solutions of First Order ODEs

1. We wish to solve the 1st order ODE

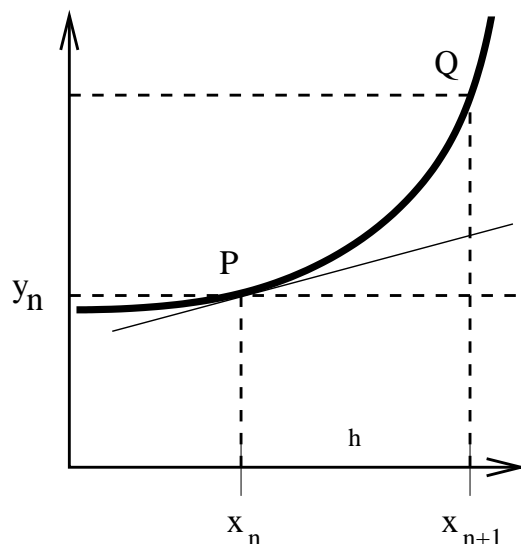
$$y' \equiv \frac{dy}{dx} = f(x, y)$$

given  $y = y_0$  at  $x = x_0$ .

2. Divide the  $x$ -axis into sections of length  $h$ . Label these points  $x_0, x_1, x_2, \dots$ :



3. Develop numerical schemes to estimate  $y_{n+1} \equiv y(x_{n+1})$  from  $x_n, y_n$  and  $f(x, y)$ .



4. The simplest is *Euler's method*, which uses the slope at  $x_n$  to approximate the curve to a local straight line, as illustrated above and given by:

$$y_{n+1} = y_n + hf(x_n, y_n) \equiv y_n + hy'_n$$

The error reduces *per step* as  $h$  is reduced by  $O(h^2)$ .

5. *Modified Euler* is similar but uses the average of the slope of the function between  $x_n$  and  $x_{n+1}$  to improve the error behaviour to  $O(h^3)$ . The slope at  $x_{n+1}$  is estimated by using the Euler method:

Slope at P =  $y'_n = f(x_n, y_n)$

Slope at Q  $\approx g_n = f(x_n + h, y_n + y'_n h)$

so

$$y_{n+1} = y_n + \frac{1}{2}h(y'_n + g_n)$$

6. *Runge-Kutta* goes further in refining the estimate to give a formulation with error per step  $O(h^5)$ , and results in

$$y_{n+1} = y_n + \frac{1}{6}(k_1 + 2k_2 + 2k_3 + k_4)$$

where

$$k_1 = hf(x_n, y_n)$$

$$k_2 = hf(x_n + \frac{1}{2}h, y_n + \frac{1}{2}k_1)$$

$$k_3 = hf(x_n + \frac{1}{2}h, y_n + \frac{1}{2}k_2)$$

$$k_4 = hf(x_n + h, y_n + k_3)$$

### 2 Power Series Approximate Solutions

#### 2.1 Picard's Method for 1st order ODEs

To find an approximate power series solution to

$$\frac{dy}{dx} = f(x, y)$$

given  $y = y_0$  at  $x = x_0$

1. Integrate formally the ODE to give

$$y(x) = y_0 + \int_{x_0}^x f[\chi, y(\chi)] d\chi$$

2. Develop a scheme of successive approximate functions  $y_n(x)$  using this integral equation, namely

$$y_{n+1}(x) = y_0 + \int_{x_0}^x f[\chi, y_n(\chi)] d\chi$$

#### 2.2 Picard's Method for 2nd order ODEs

Equations of the form:

$$\frac{d^2y}{dx^2} = g(x, y, \frac{dy}{dx})$$

given  $y = y_0$  and  $\frac{dy}{dx} = y'_0$  at  $x = x_0$ . Re-write the 2nd order

ODE as two 1st order ones by letting  $z \equiv \frac{dy}{dx}$ . This gives

$$\frac{dz}{dx} = g[x, y(x), z(x)]$$

$$\frac{dy}{dx} = z(x)$$

Then solve the above two equations using Picard's method, i.e.,

$$z_{n+1}(x) = y'_0 + \int_{x_0}^x g[\chi, y_n(\chi), z_n(\chi)] d\chi$$

$$y_{n+1}(x) = y_0 + \int_{x_0}^x z_n(\chi) d\chi$$