

# SUMMARY SHEET: PARTIAL DIFFERENTIATION

## Engineering Maths II (MAE111), 2003

**Fundamental definition:** For function  $f = f(x, y)$  of two variables  $x$  and  $y$ , the partial derivative wrt  $x$  is:

$$\frac{\partial z}{\partial x} = \lim_{\delta x \rightarrow 0} \frac{f(x + \delta x, y) - f(x, y)}{\delta x}$$

Note that this is effectively the rate of change of  $f$  in the  $x$  direction.

**Evaluation:** Use the same rules as ordinary differentiation. When differentiating wrt one variable (say  $x$ ), then treat other variables (say  $y$ ) as constant.

Example: For

$$z = f(x, y) = 4x^2 + 3xy + 5y^2$$

the first order partial derivatives are

$$\begin{aligned} \frac{\partial z}{\partial x} &= 8x + 3y \\ \frac{\partial z}{\partial y} &= 3x + 10y \end{aligned}$$

**Higher Order Derivatives:** For example, second order differential coefficients:

$$\frac{\partial^2 f}{\partial x^2}, \frac{\partial^2 f}{\partial y^2}, \frac{\partial^2 f}{\partial x \partial y}, \frac{\partial^2 f}{\partial y \partial x}.$$

Note: for most functions (actually continuous functions), the order of partial differentiation is unimportant:

$$\frac{\partial^2 f}{\partial x \partial y} = \frac{\partial^2 f}{\partial y \partial x}.$$

**Small Increments:** The approximate change in a function  $z(x, y)$  due to small changes in  $x$  and  $y$  (denoted by  $\delta x, \delta y$ ) is given by

$$\delta z \approx \frac{\partial z}{\partial x} \delta x + \frac{\partial z}{\partial y} \delta y.$$

This can be used for error estimation for a calculated quantity which depends on measurements with some fractional errors.

**Total Derivative:** For  $f(x, y)$  and if  $x = x(t)$  and  $y = y(t)$ , where  $t$  is another variable, then

$$\frac{df}{dt} = \frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt}.$$

Note mixture of partial and ordinary derivatives.

**Change of Variables:** Consider function  $z = z(x, y)$ , where the variables  $x$  and  $y$  are themselves functions of another pair of variables  $u$  and  $v$ , so that

$$x = x(u, v) \quad \text{and} \quad y = y(u, v).$$

If  $z$  is considered as a function of  $u$  and  $v$  then

$$\begin{aligned} \frac{\partial z}{\partial u} &= \frac{\partial z}{\partial x} \frac{\partial x}{\partial u} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial u} \\ \frac{\partial z}{\partial v} &= \frac{\partial z}{\partial x} \frac{\partial x}{\partial v} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial v} \end{aligned}$$

**Stationary Points:** For  $f(x, y)$  a stationary point is defined as where the rate of change is zero, so that

$$\frac{\partial f}{\partial x} = \frac{\partial f}{\partial y} = 0.$$

A stationary point may be minimum, maximum, or some other kind such as a saddle point.

For a MAXIMUM:

$$\frac{\partial^2 z}{\partial x^2} < 0 \quad \text{AND} \quad \left( \frac{\partial^2 z}{\partial x^2} \right) \left( \frac{\partial^2 z}{\partial y^2} \right) - \left( \frac{\partial^2 z}{\partial x \partial y} \right)^2 > 0$$

For a MINIMUM:

$$\frac{\partial^2 z}{\partial x^2} > 0 \quad \text{AND} \quad \left( \frac{\partial^2 z}{\partial x^2} \right) \left( \frac{\partial^2 z}{\partial y^2} \right) - \left( \frac{\partial^2 z}{\partial x \partial y} \right)^2 > 0$$

For a SADDLEPOINT:

$$\left( \frac{\partial^2 z}{\partial x^2} \right) \left( \frac{\partial^2 z}{\partial y^2} \right) - \left( \frac{\partial^2 z}{\partial x \partial y} \right)^2 < 0$$

(i.e., the function decreases in some directions, but increases in others).

**Constrained Maxima and Minima:** In order to find a maximum or minimum of a function of several variables, which **also** satisfies a further constraint: *use the constraint (or constraints) to eliminate one (or more) of the variables. And then look for maxima/minima.*

Example: A cylindrical tin is to be made out of  $600\pi$  cm<sup>2</sup> of sheet metal. What choice of radius  $r$  and height  $h$  will give the tin a maximum volume? Volume:  $V = \pi r^2 h$ , surface area (including ends)

$$S = 2\pi r h + 2\pi r^2 \quad \Rightarrow \quad h = \frac{S}{2\pi r} - r$$

Substituting for  $h$  into equation for  $V$ :

$$V = \pi r^2 \left( \frac{S}{2\pi r} - r \right) = \frac{Sr}{2} - \pi r^3$$

Then find value of  $r$  giving maximum  $V$  (remembering that  $S$  is fixed. And so on ...

**Curve Fitting by Least Squares:** For a set of  $n$  data points  $(x_i, y_i)$ , with  $i = 1, \dots, n$ , choose a suitable curve to "fit" the data, eg a straight line  $y = a + bx$  (but it could be some other function). For each data point compute the  $y$  distance from the curve, and then square and then add up for all the points:

$$S = \sum_{i=1}^n (y_i - a - bx_i)^2 = S(a, b)$$

The best ("least squares") fit is when the function  $S(a, b)$  is a minimum. Therefore the best fit is given by the values of  $a$  and  $b$  for which  $S$  is stationary:

$$\frac{\partial S}{\partial a} = 0, \quad \frac{\partial S}{\partial b} = 0.$$

### Text Book References

	Mathematics for Engineers Croft & Davison	Engineering Mathematics Stroud (4th & 5th Editions)
Partial Differentiation	–	Programme 10, 11